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Refine Search

Your wildcard search against 10000 terms has yielded the results below.

Your result set for the last L# is incomplete.

The probable cause is use of unlimited truncation. Revise your search strategy to use limited truncation.

Search Results -

Terms	Documents
L23 and ((track\$ or monitor\$ or follow\$) with speed\$) and (downshift\$ same brak\$)	. 3

US Pre-Grant Publication Full-Text Database
US Patents Full-Text Database
US OCR Full-Text Database
EPO Abstracts Database
JPO Abstracts Database
Derwent World Patents Index
IBM Technical Disclosure Bulletins

L27

Refine Search:

Refine Search:

Search History

DATE: Monday, July 10, 2006 Printable Copy Create Case

Name Query	Hit	Name	
side by	Count	result	
side		set	
DB=PGPB, USPT, USOC, EPAB, JPAB, DWPI, TDBD; THES=ASSIGNEE; PLUR=Y	ES;		
OP = OR			
L23 and ((track\$ or monitor\$ or follow\$) with speed\$) and (downshift\$ same brak\$)	3	<u>L27</u>	•
L26 L23 and (track\$ with speed\$) and (downshift\$ same brak\$)	0	<u>L26</u>	
L23 and (track\$ with speed\$) and ((accelerat\$ or decelerat\$)) and (downshift\$ same brak\$)	.0	<u>L25</u>	
L23 and (track\$ with speed\$) and ((accelerat\$ or decelerat\$) and pedal\$) and (downshift\$ same brak\$)	0	<u>L24</u>	
<u>L23</u> 119 or 120 or 121 or 122	67	<u>L23</u>	
<u>L22</u> ('6832147' '6236929' '6360156' '6411882')[URPN]	12	<u>L22</u>	
DB=USPT; THES=ASSIGNEE; PLUR=YES; OP=OR			

Set

<u>L21</u>	(6078859 5957991 5673668 5685801 4169437 6259983 5154250 6017290 5400865 6304809 5216915 6104976 4849892 6073509 6078860 6220987 5284116 6279531 5129475 5507705 5752211 5099941 5478293 5978726 5394954 6278915 6125321 6208929 5365436 5778331 5123397 6023647 0037793 5608626 6141618 5484350 6295500 6067495 4819163 5243526 4615316 4896267 6178371 6298300 5245542 5501109 4870584)![PN]	47	<u>L21</u>
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	('6832147' '6236929' '6360156' '6411882')[ABPN1,NRPN,PN,TBAN,WKU]		<u>L20</u>
	L3 or 701/95,96.ccls	4	<u>L19</u>
	=PGPB, USPT; THES=ASSIGNEE; PLUR=YES; OP=OR	2	T 10
	L12 and (accelerat\$ and pedal\$)	_	<u>L18</u> L17
	L12 and brak\$		L17
	L15 and monitor\$		L15
	L12 and (compar [©] with torque [©])		L13
	L12 and (compar\$ with torque\$) L12 and torque\$		L13
	6374173.pn. or 20020177935 or 4870583.pn. or 5758306.pn.		L13
	=PGPB, USPT, USOC, EPAB, JPAB, DWPI, TDBD; THES=ASSIGNEE; PLUR=YES;	7	1/12
OP=C			
<u>L11</u>	L10 and shift\$	13	<u>L11</u>
<u>L10</u>	L9 and down\$	23	<u>L10</u>
<u>L9</u>	L6 or L7	41	<u>L9</u>
<u>L8</u>	L6 and L7	34	<u>L8</u>
<u>L7</u>	L5 and @ad<=20021106	41	<u>L7</u>
<u>L6</u>	L5 and @pd<=20021106	34	<u>L6</u>
<u>L5</u>	L1 AND (track\$ with speed)	66	<u>L5</u>
<u>L4</u>	L3 AND (track\$ with speed)	0	<u>L4</u>
<u>L3</u>	L1 AND L2	4	<u>L3</u>
<u>L2</u>	(477/110).CCLS.	435	<u>L2</u>
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END OF SEARCH HISTORY

Hit List

Your wildcard search against 10000 terms has yielded the results below. First Hit

Your result set for the last L# is incomplete.

The probable cause is use of unlimited truncation. Revise your search strategy to use limited truncation.

Generate Collection Clear **Print** Fwd Refs **Bkwd Refs** Generate OACS

Search Results - Record(s) 1 through 3 of 3 returned.

☐ 1. Document ID: US 5778331 A

L27: Entry 1 of 3

File: USPT

Jul 7, 1998

US-PAT-NO: 5778331

DOCUMENT-IDENTIFIER: US 5778331 A

TITLE: Kickdown delay in cruise control for automatic transmission



☐ 2. Document ID: US 5685801 A

L27: Entry 2 of 3

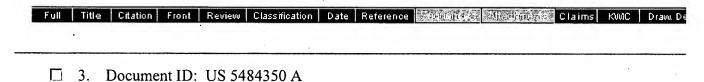
File: USPT

Nov 11, 1997

US-PAT-NO: 5685801

DOCUMENT-IDENTIFIER: US 5685801 A

TITLE: Cruise control overspeed reduction with automatic transmission

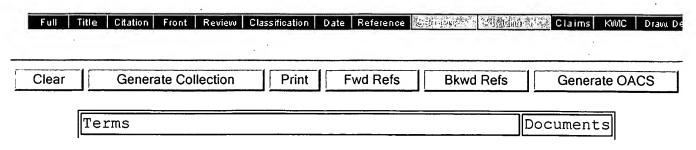


L27: Entry 3 of 3 File: USPT Jan 16, 1996

US-PAT-NO: 5484350

DOCUMENT-IDENTIFIER: US 5484350 A

TITLE: Control system for vehicle automatic transmission



L23 and	((track\$	or moni	tor\$	or	follow\$)	with	3
speed\$)	and (dow	nshift\$	same	bra	ak\$)		

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L27: Entry 1 of 3

File: USPT

Jul 7, 1998

US-PAT-NO: <u>5778331</u>

DOCUMENT-IDENTIFIER: US 5778331 A

TITLE: Kickdown delay in cruise control for automatic transmission

DATE-ISSUED: July 7, 1998

INVENTOR-INFORMATION:

NAME CITY STATE ZIP CODE COUNTRY

Leising; Maurice B. Clawson MI
Benford; Howard L. Bloomfield Hills MI
Dourra; Hans A. Dearborn Heights MI

ASSIGNEE-INFORMATION:

NAME CITY STATE ZIP CODE COUNTRY TYPE CODE

Chrysler Corporation Auburn Hills MI 02

APPL-NO: 08/663822 [PALM]
DATE FILED: June 14, 1996

INT-CL-ISSUED: [06] <u>G06</u> <u>G</u> <u>7/70</u>

US-CL-ISSUED: 701/66; 701/53, 701/58, 701/93, 477/148, 477/149, 477/108 US-CL-CURRENT: 701/66; 477/108, 477/148, 477/149, 701/53, 701/58, 701/93

FIELD-OF-CLASSIFICATION-SEARCH: 364/424.08, 364/424.081, 364/424.082, 364/424.083, 364/424.085, 364/424.041, 364/426.043, 477/108, 477/105, 477/110, 477/107, 477/111, 477/120, 477/65, 477/131, 477/128, 74/335, 74/336R
See application file for complete search history.

PRIOR-ART-DISCLOSED:

U.S. PATENT DOCUMENTS

Search ALL

Clear 3

PAT-NO	ISSUE-DATE	PATENTEE-NAME	US-CL
<u>4314340</u>	February 1982	Miki et al.	364/424.091
4414863	November 1983	Heino	477/63
4658929	April 1987	Katou et al.	180/175
<u>4709595</u>	December 1987	Hayama	477/108
<u>4875391</u>	October 1989	Leising et al.	364/424.08
	4314340 4414863 4658929 4709595	4314340 February 1982 4414863 November 1983 4658929 April 1987 4709595 December 1987	4314340 February 1982 Miki et al. 4414863 November 1983 Heino 4658929 April 1987 Katou et al. 4709595 December 1987 Hayama

Search Selected

4905545	March 1990	Leising et al.	364/424.08
4951200	August 1990	Leising et al.	364/424.08
<u>5051905</u> '	September 1991	Yoshida	364/424.082
5053963	October 1991	Mack	364/424.082
5393277	February 1995	White et al.	477/108
5468198	November 1995	Holbrook et al.	477/143
5669850	September 1997	Dourra et al.	477/108

ART-UNIT: 364

PRIMARY-EXAMINER: Louis-Jacques; Jacques H.

ATTY-AGENT-FIRM: Calcaterra; Mark P.

ABSTRACT:

An interactive cruise control system and method for providing automatic speed control of a vehicle with improved shifting of an automatic transmission. The system and method controls speed of a vehicle equipped with cruise control and minimizes downshifts in an automatic transmission of the vehicle. Vehicle speed is detected and compared with a setpoint speed which is associated with the cruise control system. Transmission gear shifting is determined based on predetermined shift schedule points. Determined transmission gear downshifts are prevented for a kickdown delay period based on vehicle speed loss and the presence of vehicle deceleration. Also provided is an overspeed reduction method for causing a transmission downshift during an overspeed condition with the throttle closed. Further, the system provides hunting prevention between both second gear and third gear as well as between third gear and fourth gear for a four speed automatic transmission.

11 Claims, 11 Drawing figures

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L27: Entry 1 of 3

File: USPT

Jul 7, 1998

DOCUMENT-IDENTIFIER: US 5778331 A

TITLE: Kickdown delay in cruise control for automatic transmission

Brief Summary Text (7):

A vehicle is generally equipped with an electronic engine control system for controlling the operation of the engine and drivetrain of the vehicle. The electronic control system includes a microcomputer-based transmission control module capable of receiving and monitoring input signals indicative of various vehicle operating conditions such as engine speed, torque converter turbine speed, vehicle output speed, throttle angle position, brake application, hydraulic pressures, a driver selected gear or operating condition (PRNODDL), engine coolant temperature and/or the ambient air temperature. Based on the information contained in the monitored signals, the controller generates command or control signals for causing actuation of solenoid-actuated valves to regulate the application and release of fluid pressure to and from apply cavities of clutches or frictional elements of the transmission. Accordingly, the controller is typically programmed to execute predetermined shift schedules stored in memory of the controller through appropriate command signals to the solenoid-actuated valves.

Detailed Description Text (30):

The interactive cruise control system 10 further includes an overspeed reduction feature as shown by methodology 200 in FIGS. 8A and 8B. Overspeed reduction methodology 200 operates to provide an automatic <u>downshift</u> of the automatic transmission to increase engine braking during the presence of an overspeed condition while operating the vehicle in cruise control. This advantageously <u>brakes</u> the vehicle to reduce speed so as to bring the vehicle speed to within an acceptable speed range according to the setpoint speed of the cruise control system 10.

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L27: Entry 2 of 3

File: USPT

Nov 11, 1997

US-PAT-NO: 5685801

DOCUMENT-IDENTIFIER: US 5685801 A

TITLE: Cruise control overspeed reduction with automatic transmission

DATE-ISSUED: November 11, 1997

INVENTOR-INFORMATION:

NAME CITY. STATE ZIP CODE COUNTRY

Benford; Howard L. Bloomfield Hills MI
Dourra; Hans A. Dearborn Heights MI
Leising; Maurice B. Clawson MI

ASSIGNEE-INFORMATION:

NAME CITY STATE ZIP CODE COUNTRY TYPE CODE

Chrysler Corporation Auburn Hills MI 02

APPL-NO: 08/663497 [PALM]
DATE FILED: June 14, 1996

INT-CL-ISSUED: [06] <u>B60 K</u> 41/08

US-CL-ISSUED: 477/108 US-CL-CURRENT: 477/108

FIELD-OF-CLASSIFICATION-SEARCH: 477/108

See application file for complete search history.

PRIOR-ART-DISCLOSED:

U.S. PATENT DOCUMENTS

•	Search Selected	Search ALL Clear	
	, TOOLIN DAWN		
PAT-NO	ISSUE-DATE	PATENTEE-NAME	US-CL
4535865	August 1985	Tanigawa et al.	477/108
4716789	January 1988	Suzuki	477/108
<u>4736813</u>	April 1988	Hayamam et al.	477/108
4875391	October 1989	Leising et al.	
4905545	March 1990	Leising et al.	
4951200	August 1990	Leising et al.	

4982805

January 1991

Naitou et al.

477/108

ART-UNIT: 352

PRIMARY-EXAMINER: Wright; Dirk

ATTY-AGENT-FIRM: Calcaterra; Mark P.

ABSTRACT:

An interactive cruise control system and method for providing automatic speed control of a vehicle with improved shifting of an automatic transmission. The system and method controls speed of a vehicle equipped with cruise control and minimizes downshifts in an automatic transmission of the vehicle. Vehicle speed is detected and compared with a setpoint speed which is associated with the cruise control system. Transmission gear shifting is determined based on predetermined shift schedule points. Determined transmission gear downshifts are prevented for a kickdown delay period based on vehicle speed loss and the presence of vehicle deceleration. Also provided is an overspeed reduction method for causing a transmission downshift during an overspeed condition with the throttle closed. Further, the system provides hunting prevention between both second gear and third gear as well as between third gear and fourth gear of a four speed automatic transmission.

9 Claims, 11 Drawing figures

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L27: Entry 2 of 3 File: USPT Nov 11, 1997

DOCUMENT-IDENTIFIER: US 5685801 A

TITLE: Cruise control overspeed reduction with automatic transmission

Brief Summary Text (7):

A vehicle is generally equipped with an electronic engine control system for controlling the operation of the engine and drivetrain of the vehicle. The electronic control system includes a microcomputer-based transmission control module capable of receiving and monitoring input signals indicative of various vehicle operating conditions such as engine speed, torque converter turbine speed, output vehicle speed, throttle angle position, brake application, hydraulic pressures, a driver selected gear or operating condition (PRNODDL), engine coolant temperature and/or the ambient air temperature. Based on the information contained in the monitored signals, the controller generates command or control signals for causing actuation of solenoid-actuated valves to regulate the application and release of fluid pressure to and from apply cavities of clutches or frictional elements of the transmission. Accordingly, the controller is typically programmed to execute predetermined shift schedules stored in memory of the controller through appropriate command signals to the solenoid-actuated valves.

Brief Summary Text (16):

To achieve the foregoing objectives, the present invention is an interactive cruise control system and method for providing automatic speed control of a vehicle with improved shifting of an automatic transmission. The system and method controls speed of a vehicle equipped with cruise control and reduces overspeed conditions by downshifting the automatic transmission. Vehicle speed is detected and compared with a setpoint speed which is associated with the cruise control system. The cruise control system determines when the detected vehicle speed exceeds the setpoint speed by an overspeed value and further monitors the position of the throttle of the vehicle and determines if the throttle is in a substantially closed position. A downshift of the automatic transmission is caused when the vehicle speed exceeds the setpoint speed by the overspeed value while the throttle position is substantially closed so as to brake the vehicle to attempt to bring the vehicle speed closer to the setpoint speed.

Detailed Description Text (30):

The interactive cruise control system 10 further includes an overspeed reduction feature as shown by methodology 200 in FIGS. 8A and 8B. Overspeed reduction methodology 200 operates to provide an automatic <u>downshift</u> of the automatic transmission to increase engine braking during the presence of an overspeed condition while operating the vehicle in cruise control. This advantageously <u>brakes</u> the vehicle to reduce speed so as to bring the vehicle speed to within an acceptable speed range according to the setpoint speed of the cruise control system 10.

CLAIMS:

1. A method of controlling speed of a vehicle equipped with an automatic transmission and cruise speed control, said method comprising the steps of:

storing a setpoint speed associated with the cruise speed control;

detecting speed of the vehicle;

comparing the detected speed of the vehicle with the setpoint speed;

determining when the detected vehicle speed exceeds the setpoint speed by an overspeed value;

monitoring throttle position of the vehicle and determining if a throttle closed condition exists; and

causing a transmission <u>downshift</u> in the automatic transmission when the vehicle speed exceeds the setpoint speed by said overspeed amount while the throttle position is substantially closed so as to brake the vehicle.

4. A method of controlling speed of a vehicle equipped with an automatic transmission and cruise speed control so as to maintain a driver selected setpoint speed by causing engine braking for an overspeed condition, said method comprising the steps of:

storing a setpoint speed associated with the cruise speed control;

detecting speed of the vehicle;

comparing the detected speed of the vehicle with the setpoint speed;

determining when the detected vehicle speed exceeds the setpoint speed by an predetermined overspeed value;

monitoring throttle position of the vehicle and determining if a substantially closed throttle condition exists which is indicative of an attempt to reduce vehicle speed; and

causing a transmission $\underline{\text{downshift}}$ in the automatic transmission when the vehicle speed exceeds the setpoint speed by said overspeed amount while the throttle position is substantially closed so as to $\underline{\text{brake}}$ the vehicle in an attempt to overcome the overspeed condition.

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L27: Entry 3 of 3

File: USPT

Jan 16, 1996

US-PAT-NO: 5484350

DOCUMENT-IDENTIFIER: US 5484350 A

TITLE: Control system for vehicle automatic transmission

DATE-ISSUED: January 16, 1996

INVENTOR-INFORMATION:

NAME CITY STATE ZIP CODE COUNTRY Ishikawa; Hiroshi . .Wako JP Furukawa; Hideo Wako JP Shimizu; Masatoshi Wako JP Nakauchi; Norio Wako JP

ASSIGNEE-INFORMATION:

NAME STATE ZIP CODE COUNTRY TYPE CODE

Honda Giken Kogyo Kabushiki Kaisha Tokyo JP 03

APPL-NO: 08/295546 DATE FILED: August 25, 1994

FOREIGN-APPL-PRIORITY-DATA:

COUNTRY APPL-NO APPL-DATE

JΡ 5-238896 August 31, 1993

INT-CL-ISSUED: [06] <u>F16</u> <u>H</u> <u>59/04</u>, <u>F16</u> <u>H</u> <u>59/62</u>

US-CL-ISSUED: 477/97; 477/120 US-CL-CURRENT: 477/97; 477/120

FIELD-OF-CLASSIFICATION-SEARCH: 477/97, 477/120 See application file for complete search history.

PRIOR-ART-DISCLOSED:

U.S. PATENT DOCUMENTS

Search Selected Search ALL Clear PAT-NO ISSUE-DATE PATENTEE-NAME

4285252 August 1981 Yamaki et al. 4795015 January 1989 Hibino et al. 477/97

US-CL

<u>4943921</u>

July 1990

Baltusis et al.

477/97

4947971

August 1990

Tanaka

477/97

FOREIGN PATENT DOCUMENTS

FOREIGN-PAT-NO

PUBN-DATE

COUNTRY

CLASS

5-17626

March 1993

JP

ART-UNIT: 352

PRIMARY-EXAMINER: Wright; Dirk

ATTY-AGENT-FIRM: Armstrong, Westerman, Hattori, McLeland & Naughton

ABSTRACT:

A control system of a vehicle automatic transmission in which an engine load and a vehicle speed are detected and used to determine a vehicle acceleration in accordance with the preestablished characteristics. An actual vehicle acceleration is at the same time calculated in response to the detected vehicle speed. The difference therebetween is then calculated and the calculated value is added to a difference calculated earlier to obtain an average therebetween. Five gear shifting scheduling maps, for example one for moderate hill climbing, one for level-road running, one for steep hill descent, are preestablished and in response to the average obtained, one of the maps is selected. A gear shifting is controlled based on the selected map. The actual vehicle acceleration is corrected by the altitude where the vehicle is traveling so as to compensate for the engine output decrease due to the charging efficiency drop.

5 Claims, 33 Drawing figures

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L27: Entry 3 of 3

File: USPT

Jan 16, 1996

DOCUMENT-IDENTIFIER: US 5484350 A

TITLE: Control system for vehicle automatic transmission

Detailed Description Text (51):

If step S716 determines that the current map (number) is the level-road running map (number), the program passes to step S718 in which the vehicle speed is compared with a prescribed value YKUV1, and if it determines that the current map (number) is not the level-road running map (number), i.e if it determines that the current map (number) is the moderate hill climbing map (number), the program passes to step S720 in which the vehicle speed is compared with another prescribed value YKUV3. If the vehicle speed is found to be equal to or greater than the prescribed value in either of steps S718 or S720, the program skips to step S712 and map switching is carried out. This will be better understood from FIG. 24. As was explained earlier, the breadth of the third gear range is greater in the maps for hill climbing and descent than in the map for level-road running. As shown specifically in FIG. 24, the boundary vehicle speed for shifting from third gear to fourth gear when the map is changed from that for level-road running to that for moderate hill descent is set as vehicle speed YKUV1. Since there is therefore no possibility of a shift-down when the vehicle speed is equal to or higher than the boundary speed, the program is passed to step S712 for switching maps. On the other hand, if the vehicle speed is found to be below the boundary level, the possibility of a downshifting exists and, therefore, a determination is carried out in the following steps as to whether or not one will. While FIG. 24 relates only to the case of switching from the level-road running map (#2) to the moderate hill descent map (#3), switching from the moderate hill descent map (#3) to the steep hill descent map (#4) is handled in a similar manner.

Detailed Description Text (56):

This is conducted notwithstanding that the driver has applied the brakes and wants to slow down and is for preventing map switching and thus avoiding an abrupt engine braking effect (owing to downshifting) which would otherwise occur at an intensity that increases in proportion to the vehicle speed at the time of the shift-down. Therefore, it is arranged such that more degree of actual deceleration data is required for map switching as the vehicle speed becomes higher. Thus, the map is changed to enable downshifting only when it is determined from the result of the comparison that rapid deceleration is intended. In other words, the braking operation indicates that the driver wants to slow down. At that condition, if the braking suffices the driver's intended deceleration, to conduct shift-down to make the vehicle to further slow down will not meet the driver's intention and hence is avoided. Moreover, downshifting makes the vehicle to travel at a lower gear (i.e., run at a greater gear ratio) than usual and as a result engine speed rises so that the engine becomes noisier. In particular, with the increasing steepness of the downhill vehicle speed rises and engine speed tends to rise. The degree of deceleration data is therefore predetermined taking the vehicle speed and road profile (grade) into account in such a manner that the degree of deceleration data grows with increasing downhill grade and/or with increasing vehicle speed so that the addition of MAPS at step S712 is hard to occur, i.e., switching to the maps for hill descent having the broader low gear region is not likely to occur.